

THE Z-TRANSFORM*

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1 The z -transform

We introduced the z -transform before as

$$H(z) = \sum_{k=-\infty}^{\infty} h[k] z^{-k} \quad (1)$$

where z is a complex number. When $H(z)$ exists (the sum converges), it can be interpreted as the “response” of an LSI system with impulse response $h[n]$ to the input of z^n . The z -transform is useful mostly due to its ability to simplify system analysis via the following result.

Theorem

If $y = h * x$, then $Y(z) = H(z)X(z)$.

Proof

First observe that

$$\begin{aligned} \sum_{n=-\infty}^{\infty} y[n] z^{-n} &= \sum_{n=-\infty}^{\infty} \left(\sum_{k=-\infty}^{\infty} x[k] h[n-k] \right) z^{-n} \\ &= \sum_{k=-\infty}^{\infty} x[k] \left(\sum_{n=-\infty}^{\infty} h[n-k] z^{-n} \right) \end{aligned} \quad (2)$$

Let $m = n - k$, and note that $z^{-n} = z^{-m} \cdot z^{-k}$. Thus we have

$$\begin{aligned} \sum_{n=-\infty}^{\infty} y[n] z^{-n} &= \sum_{k=-\infty}^{\infty} x[k] \left(\sum_{n=-\infty}^{\infty} h[m] z^{-m} \right) z^{-k} \\ &= \sum_{k=-\infty}^{\infty} x[k] H(z) z^{-k} \\ &= H(z) \left(\sum_{k=-\infty}^{\infty} x[k] z^{-k} \right) \\ &= H(z) X(z) \end{aligned} \quad (3)$$

This yields the “transfer function”

$$H(z) = \frac{Y(z)}{X(z)}. \quad (4)$$

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